



VectorNav VN-100

Next Generation Embedded Navigation

PRODUCT OVERVIEW

The VN-100 is a miniature, light weight, low power, high-performance Attitude and Heading Reference System (AHRS) available in a surface mount package or aluminum encased Rugged module. Incorporating the latest in solid-state MEMS technology, the VN-100 combines accelerometers, gyros, magnetometers and a 32-bit processor into an extremely compact design.

The VN-100 computes and outputs a real-time, drift-free attitude solution (i.e. 3D orientation) that is continuous over a complete range of 360° motion. All VN-100 sensors go through a rigorous calibration process at the VectorNav production facility to ensure the highest quality attitude estimates and inertial measurements. The small size, high performance, and cost-effectiveness of the VN-100 provides unprecedented opportunities for embedded navigation.





HIGHLIGHTS

- > Attitude & Inertial Data at 200 Hz
- Continuous Attitude Solution Over Complete 360° Range of Motion
- Static Accuracy better than 0.5° in Pitch/Roll, 2° in Heading
- Individually Calibrated for Bias,
 Scale Factor, Misalignment, &
 Gyro G-Sensitivity Errors
- Available with Full Temperature
 Compensation (-40°C to +85°C)
- ➤ Dimensions: 22 x 24 x 3 mm
- > Weight: 3 grams
- Surface Mount Package (30-pin LGA)

FEATURES

- ➤ On-Board Gyro Drift Compensation
- Real-Time Magnetic & Acceleration
 Disturbance Rejection
- Adaptive Signal Filtering
- Dynamic Filter Tuning
- On-Board Hard & Soft Iron Compensation
- Multi-Sensor Synchronization
- Inputs for External Magnetometers or Velocity Measurements (Airspeed Measurements, GPS)

TECHNICAL SPECIFICATIONS

Attitude & Heading

Range: Heading, Roll: ±180 °
Range: Pitch: ±90 °
Static Accuracy (heading): <2.0 °
Static Accuracy (pitch/roll): <0.5 °
Angular Resolution: <0.05 °
Maximum Output Rate: 200 Hz

IMU - Angular Rate

 $\begin{array}{lll} \mbox{Range - Standard:} & \pm 500\ \mbox{°/s} \\ \mbox{Range - Extended':} & \pm 2000\ \mbox{°/s} \\ \mbox{Linearity:} & < 0.1\ \mbox{\% FS} \\ \mbox{Noise Density:} & 0.005\ \mbox{°/s} / \mbox{Hz} \\ \mbox{Bandwidth:} & 256\ \mbox{Hz} \\ \end{array}$

±0.05°

IMU - Acceleration

Alignment Error:

Range - Standard: $\pm 8 \text{ g}$ Range - Extended*: $\pm 16 \text{ g}$ Linearity: < 0.5 % FSNoise Density: $400 \text{ mg}/\sqrt{\text{Hz}}$ Bandwidth: 260 HzAlignment Error: $\pm 0.05 \degree$

IMU - Magnetic

Range - Standard: ±2.5 Gauss
Range - Extended*: ±8 Gauss
Linearity: <0.1 %

Noise Density: 140 μ Gauss/ \sqrt{Hz}

Bandwidth: 200 Hz
Alignment Error: ±0.05 °

IMU - Pressure

 Range:
 10 to 1200 mbar

 Resolution:
 0.042 mbar

 Accuracy:
 ±1.5 mbar

 Error Band:
 ±2.5 mbar

 Bandwidth:
 200 Hz

Environment

Operating Temp: -40°C to 85°C Storage Temp: -40°C to 85°C

Electrical

Input Voltage: 3.2 V to 5.5 V

Current Draw: 50 mA

Power Consumption: 165 mW @ 3.3V

Digital Interface: Serial TTL, SPI

Physical (Surface Mount Part)

 Size: (in)
 0.87 x 0.95 x 0.12

 (mm)
 22 x 24 x 3

 Weight:
 3 g

 Footprint:
 30-pin LGA

VN-100 DEVELOPMENT KITS



- > VN-100 Development Board
 - Pre-Soldered VN-100 Surface Mount Part with USB & RS-232 Interfaces
 - 30-Pin Header for Easy Prototyping



- VN-100 Rugged Development Kit
 - USB & Serial Adapter Cables
 - Connection Tool & Carrying Case
 - Powerful, User-Friendly Sensor Explorer 2.0 GUI
 - Software Development Kit: C/C++, .Net & MATLAB Libraries

VN-100 DEVELOPMENT TOOLS

- Sensor Explorer GUI
 - Powerful & user-friendly GUI allows you to display sensor output as a 3D object, graph inertial data, configure sensor settings, perform data-logging, & more
- Software Development Kit
 - Interface via C/C++, .NET, & MATLAB development environments
- Online Library
 - A large collection of inertial navigation knowledge & application notes is provided on our website to help maximize VN-100 performance for your application

^{*} Contact VectorNav for pricing and availability of extended range versions.